

Advances In Gyroscope Technologies By Mario N Armenise

Presents the mathematical framework, technical language, and control systems know-how needed to design, develop, and instrument micro-scale whole-angle gyroscopes. This comprehensive reference covers the technical fundamentals, mathematical framework, and common control strategies for degenerate mode gyroscopes, which are used in high-precision navigation applications. It explores various energy loss mechanisms and the effect of structural imperfections, along with requirements for continuous rate integrating gyroscope operation. It also provides information on the fabrication of MEMS whole-angle gyroscopes and the best methods of sustaining oscillations. *Whole-Angle Gyroscopes: Challenges and Opportunities* begins with a brief overview of the two main types of Coriolis Vibratory Gyroscopes (CVGs): non-degenerate mode gyroscopes and degenerate mode gyroscopes. It then introduces readers to the Foucault Pendulum analogy and a review of MEMS whole angle mode gyroscope development. Chapters cover: dynamics of whole-angle coriolis vibratory gyroscopes; fabrication of whole-angle coriolis vibratory gyroscopes; energy loss mechanisms of coriolis vibratory gyroscopes; and control strategies for whole-angle coriolis vibratory gyroscopes. The book finishes with a chapter on conventionally machined micro-machined gyroscopes, followed by one on micro-wineglass gyroscopes. In addition, the book: Lowers barrier to entry for aspiring scientists and engineers by providing a solid understanding of the fundamentals and control strategies of degenerate mode gyroscopes Organizes mode-matched mechanical gyroscopes based on three classifications: wine-glass, ring/disk, and mass spring mechanical elements Includes case studies on conventionally micro-machined and 3-D micro-machined gyroscopes *Whole-Angle Gyroscopes* is an ideal book for researchers, scientists, engineers, and college/graduate students involved in the technology. It will also be of great benefit to engineers in control systems, MEMS production, electronics, and semi-conductors who work with inertial sensors.

"Realizing the potential of the fiber optic gyro, like the ring laser gyro, has been a long and expensive process. Many researchers have made important enabling contributions, and many more engineers have worked diligently for many years on solving the problems associated with realizing viable inertial navigation and guidance produce at affordable costs. This book arose from efforts to form a special session to commemorate the fortieth anniversary of the first hardware demonstration of the fiber gyro in 1976 by Vali and Shorthill. The chapters contain contributions from key engineers and scientists who have worked from as early as 1977 to the present on manufacturing high-performance fiber gyros for many applications"--

This book highlights an analytical solution for the dynamics of axially symmetric rotating objects. It also presents the theory of gyroscopic effects, explaining their physics and using mathematical models of Euler's form for the motion of movable spinning objects to demonstrate these effects. The major themes and approaches are represented by the spinning disc and the action of the system of interrelated inertial torques generated by the centrifugal, common inertial, Coriolis forces, as well as the change in their angular momentum. These torques constitute the fundamental principles of the mechanical gyroscope theory that can be used for any rotating objects, like rings, cones, spheres, paraboloids and propellers of different designs. Lastly, the mathematical models for the gyroscopic effects are validated by practical tests. This book presents the proceedings of the 3rd International Conference of IFToMM ITALY, held online on September 9-11, 2020. It includes peer-reviewed papers on the latest advances in mechanism and machine science, discussing topics such as biomechanical engineering, computational kinematics, the history of mechanism and machine science, gearing and transmissions, multi-body dynamics, robotics and mechatronics, the dynamics of machinery, tribology, vibrations, rotor dynamics and vehicle dynamics. A valuable, up-to-date resource, it offers an essential overview of the subject for scientists and practitioners alike, and will inspire further investigations and research.

Sensors is the first self-contained series to deal with the whole area of sensors. It describes general aspects, technical and physical fundamentals, construction, function, applications and developments of the various types of sensors. This final volume of the series uncovers trends in sensor technology and gives a comprehensive overview of the sensor market. The use of sensors in microsystems and in vacuum microelectronic as well as in acoustic wave devices is discussed. Present and emerging applications of sensors in aerospace, environmental, automotive, and medical industries, among others, are described. This volume is an indispensable reference work for both specialists and newcomers, researchers and developers

This proceedings volume gathers the outcomes of the International Conference on Engineering Research and Applications (ICERA 2019), which was held at Thai Nguyen University of Technology, Vietnam, on December 1–2, 2019 and provided an international forum for disseminating the latest theories and practices in engineering research and applications. The conference focused on original research work in a broad range of areas, including Mechanical Engineering, Materials and Mechanics of Materials, Mechatronics and Micromechatronics, Automotive Engineering, Electrical and Electronics Engineering, and Information and Communication Technology. By sharing the latest advances in these fields, the book will help academics and professionals alike to revisit their thinking on sustainable development.

From the beginnings of the International Forum on Advanced Microsystems for Automotive Application (AMAA) to the recent 11th AMAA Forum, enormous progress has been made in reducing casualties, emissions and in increasing comfort and performance. In many cases Microsystems provided key functions for this progress. This publication is a cut-out of new technological priorities in the area of microsystems-based smart devices, taking a mid-term perspective of future smart systems applications in automobiles.

Written by one of the field's leading experts, this landmark reference presents a thorough system analysis of the fiber-optic gyroscope (FOG), describing the concepts that have emerged as the preferred solutions for obtaining a practical device. This book's first edition was published in the early 1990's. If the basic design rules of the FOG have remained unchanged, the technology has certainly matured, and the expectations presented in the first edition have been largely exceeded. This second edition is updated throughout, featuring new content on Allan variance; testing with optical coherence domain polarimetry; the Shupe effect; and rare-Earth doped fiber ASE sources. In addition, brand new comprehensive appendixes cover the optics, single-mode fiber optics, and integrated optics necessary to understand the fiber gyro and provide an appropriate vocabulary for communicating with electronic component designers.

Inertial navigation is widely used for the guidance of aircraft, missiles ships and land vehicles, as well as in a number of novel applications such as surveying underground pipelines in drilling operations. This book discusses the physical principles of inertial navigation, the associated growth of errors and their compensation. It draws current technological developments, provides an indication of potential future trends and covers a broad range of applications. New chapters on MEMS (microelectromechanical systems) technology and inertial system applications are included.

This monograph collects and critically reviews the main results obtained by the scientific community in gyroscope technologies research field. It describes architectures, design techniques and fabrication technology of angular rate sensors proposed in literature. MEMS, MOEMS, optical and mechanical technologies are discussed together with achievable performance. The book also considers future research trends aimed to cover special applications. The book is intended for researchers and Ph.D. students interested in modelling, design and fabrication of gyros. The book may be a useful education support in some university courses focused on gyro technologies.

Kinematic Systems in Geodesy, Surveying, and Remote Sensing provides a state-of-the-art discussion on the use of the Global Positioning System (GPS) in combination with Inertial Navigation Systems (INS) for detailed sensing of the Earth's surface. Divided into two parts, the book first discusses GPS/INS with respect to theory and modelling, equipment trends, estimation methods and quality control, algorithms, and software trends. It then describes the applications of these kinematic systems to positioning and navigation, modelling and measurement of gravity, gravity gradiometry, and altitude. This collection of 63 presentations documents the symposium of the same name held in Banff, Alberta, September 1990. It is the sixth volume of the International Association of Geodesy Symposia series published by Springer-Verlag New York.

Microsystems are an important success factor in the automobile industry. In order to fulfil the customers' requests for safety convenience and vehicle economy, and to satisfy environmental requirements, microsystems are becoming indispensable. Thus a large number of microsystem applications came into the discussion. With the international conference AMAA 2000, VDI/VDE-IT provides a platform for the discussion of all MST relevant components for automotive applications. The conference proceedings gather the papers by authors from automobile suppliers and manufacturers.

This book covers recent topics on gyroscopes. It briefly introduces the history of gyroscopes, and presents a concise analysis of the main types. The classical structure and main performance parameters of an interferometric fiber-optic gyroscope and an integrated optics passive-resonator gyroscope are analyzed. The developmental progress of a fiber optic gyroscope and its research situation in the United States, Japan, France, and other major developing countries are also presented. An effective autoregressive moving average model was invented to reduce MEMS gyroscope noise behavior. A discrete-time nonlinear attitude tracking control system was verified to achieve the agility and large-angle attitude maneuvers of spacecraft by numerical simulations. MEMS gyroscopes were experimentally demonstrated to be effective tools for gait analysis and to reduce the cost of revealing underlying pathologies.

This report is designed to present the research programs of the Air Force Office of Scientific Research for the information of users of Air Force research, for scientific investigators working in the same or in allied fields, and for the military, scientific and academic, and Government communities at large.

A NATO Advanced Research Workshop (ARW) entitled "Advanced Materials and Technologies for Micro/Nano Devices, Sensors and Actuators" was held in St. Petersburg, Russia, from June 29 to July 2, 2009. The main goal of the Workshop was to examine (at a fundamental level) the very complex scientific issues that pertain to the use of micro- and nano-electromechanical systems (MEMS and NEMS), devices and technologies in next generation commercial and defense-related applications. Micro- and nano-electromechanical systems represent rather broad and diverse technological areas, such as optical systems (micromirrors, waveguides, optical sensors, integrated subsystems), life sciences and lab equipment (micropumps, membranes, lab-on-chip, membranes, microfluidics), sensors (bio-sensors, chemical sensors, gas-phase sensors, sensors integrated with electronics) and RF applications for signal transmission (variable capacitors, tunable filters and antennas, switches, resonators). From a scientific viewpoint, this is a very multi-disciplinary field, including micro- and nano-mechanics (such as stresses in structural materials), electronic effects (e. g. charge transfer), general electrostatics, materials science, surface chemistry, interface science, (nano)tribology, and optics. It is obvious that in order to overcome the problems surrounding next-generation MEMS/NEMS devices and applications it is necessary to tackle them from different angles: theoreticians need to speak with mechanical engineers, and device engineers and modelers to listen to surface physicists. It was therefore one of the main objectives of the workshop to bring together a multidisciplinary team of distinguished researchers.

This thesis develops next-generation multi-degree-of-freedom gyroscopes and inertial measurement units (IMU) using micro-electromechanical-systems (MEMS) technology. It covers both a comprehensive study of the physics of resonator gyroscopes and novel micro/nano-fabrication solutions to key performance limits in MEMS resonator gyroscopes. Firstly, theoretical and experimental studies of physical phenomena including mode localization, nonlinear behavior, and energy dissipation provide new insights into challenges like quadrature errors and flicker noise in resonator gyroscope systems. Secondly, advanced designs and micro/nano-fabrication methods developed in this work demonstrate valuable applications to a wide range of MEMS/NEMS devices. In particular, the HARPSS+ process platform established in this thesis features a novel slanted nano-gap transducer, which enabled the first wafer-level-packaged single-chip IMU prototype with co-fabricated high-frequency resonant triaxial gyroscopes and high-bandwidth triaxial micro-gravity accelerometers. This prototype demonstrates performance amongst the highest to date, with unmatched robustness and potential for flexible substrate integration and ultra-low-power operation. This thesis shows a path toward future low-power IMU-based applications including wearable inertial sensors, health informatics, and personal inertial navigation.

2010 First International Conference on Electrical and Electronics Engineering was held in Wuhan, China December 4-5. Advanced Electrical and Electronics Engineering book contains 72 revised and extended research articles written by prominent researchers participating in the conference. Topics covered include, Power Engineering, Telecommunication, Control engineering, Signal processing, Integrated circuit, Electronic amplifier, Nano-technologies, Circuits and networks, Microelectronics, Analog circuits, Digital circuits, Nonlinear circuits, Mixed-mode circuits, Circuits design, Sensors, CAD tools, DNA computing, Superconductivity circuits. Electrical and Electronics Engineering will offer the state of art of tremendous advances in Electrical and Electronics Engineering and also serve as an excellent reference work for researchers and graduate students working with/on Electrical and Electronics Engineering.

This book provides a comprehensive treatment of the field of modern fiber optics, beginning with the basics of the field summarized in an introductory chapter. Expert contributors then topics such as polarization effects in optical fibers; photonic crystal fibers; highly-doped optical fibers; non-linear effects; amplification and lasing in optical fibers; supercontinuum generation, Rayleigh and inelastic scattering with applications to sensing; optical fiber point sensors, and polymer optical-fiber-based sensors.

This book gathers selected high-quality research papers presented at International Conference on Advanced Computing and Intelligent Technologies (ICACIT 2021) held at NCR New Delhi, India, during March 2021, 2021, jointly organized by Galgotias University, India, and Department of Information Engineering and Mathematics Universita Di Siena, Italy. It discusses emerging topics pertaining to advanced computing, intelligent technologies, and networks including AI and machine learning, data mining, big data analytics, high-performance computing network performance analysis, Internet of things networks, wireless sensor networks, and others. The book offers a valuable asset for researchers from both academia and industries involved in advanced studies.

This book presents original contributions on the theories and practices of emerging Internet, data and Web technologies and their applicability in businesses, engineering and academia, focusing on advances in the life-cycle exploitation of data generated from the digital ecosystem data technologies that create value, e.g. for businesses, toward a collective intelligence approach. The Internet has become the most

proliferative platform for emerging large-scale computing paradigms. Among these, data and web technologies are two of the most prominent paradigms and are found in a variety of forms, such as data centers, cloud computing, mobile cloud, and mobile Web services. These technologies together create a digital ecosystem whose cornerstone is the data cycle, from capturing to processing, analyzing and visualizing. The investigation of various research and development issues in this digital ecosystem are made more pressing by the ever-increasing requirements of real-world applications that are based on storing and processing large amounts of data. The book is a valuable resource for researchers, software developers, practitioners and students interested in the field of data and web technologies.

This book is based on the 18 tutorials presented during the 28th workshop on Advances in Analog Circuit Design. Expert designers present readers with information about a variety of topics at the frontier of analog circuit design, including next-generation analog-to-digital converters, high-performance power management systems and technology considerations for advanced IC design. For anyone involved in analog circuit research and development, this book will be a valuable summary of the state-of-the-art in these areas. Provides a summary of the state-of-the-art in analog circuit design, written by experts from industry and academia; Presents material in a tutorial-based format; Includes coverage of next-generation analog-to-digital converters, high-performance power management systems, and technology considerations for advanced IC design.

Inertial navigation is widely used for the guidance of aircraft, ships, missiles and vehicles. This introduction to the system covers basic principles, system mechanics, instrumentation, computation and design analysis. The text features a particularly contemporary treatment of inertial sensors and computational techniques for error analysis. It also describes integrated systems incorporating additional navigational aids and examples of current applications in both civilian and military situations.

This book gathers papers presented at the International Joint Conference on Mechanics, Design Engineering and Advanced Manufacturing (JCM 2016), held on 14-16 September, 2016, in Catania, Italy. It reports on cutting-edge topics in product design and manufacturing, such as industrial methods for integrated product and process design; innovative design; and computer-aided design. Further topics covered include virtual simulation and reverse engineering; additive manufacturing; product manufacturing; engineering methods in medicine and education; representation techniques; and nautical, aeronautics and aerospace design and modeling. The book is divided into eight main sections, reflecting the focus and primary themes of the conference. The contributions presented here will not only provide researchers, engineers and experts in a range of industrial engineering subfields with extensive information to support their daily work; they are also intended to stimulate new research directions, advanced applications of the methods discussed, and future interdisciplinary collaborations.

Microsystems are an important success factor in the automobile industry. In order to fulfil the customers requests for safety convenience and vehicle economy, and to satisfy environmental requirements, microsystems are becoming indispensable. Thus a large number of microsystem applications came into the discussion. With the international conference AMAA 2002, VDI/VDE-IT provides a platform for the discussion of all MST relevant components for automotive applications. The conference proceedings gather the papers by authors from automobile suppliers and manufacturers.

Nonlinear dynamics has been enjoying a vast development for nearly four decades resulting in a range of well established theory, with the potential to significantly enhance performance, effectiveness, reliability and safety of physical systems as well as offering novel technologies and designs. By critically appraising the state of the art, it is now time to develop design criteria and technology for new generation products/processes operating on principles of nonlinear interaction and in the nonlinear regime, leading to more effective, sensitive, accurate, and durable methods than what is currently available. This new approach is expected to radically influence the design, control and exploitation paradigms, in a magnitude of contexts. With a strong emphasis on experimentally calibrated and validated models, contributions by top-level international experts will foster future directions for the development of engineering technologies and design using robust nonlinear dynamics modelling and analysis.

This book focuses on gyro-free inertial navigation technology, which is used to measure not only linear motion parameters but also angular rates. Since no gyroscopes are used, the key technologies, such as initial alignment, attitude resolution, and error calibration, are very different than those used in traditional methods. Discussing each key technology in gyro-free inertial navigation system (GFINS) manufacture in a separate chapter, the book features easy-to-understand, detailed illustrations, to allow all those involved in inertial navigation to gain a better grasp of GFINS manufacture, including accelerometer setting principles; initial alignment; quaternion-based, attitude resolution algorithms; and accelerometer de-noise methods.

The fiber laser, with its humble beginning in the late 1980s, has undergone tremendous development in the past decade or so, transforming itself from a research curiosity to a major force in modern manufacturing. Today, it is revolutionizing our economy by fundamentally changing the way we mark, machine, and process materials on an industrial scale. The recent development of high-power fiber lasers is also fundamentally shaping a wide range of other areas from physical sciences and medicine to geology and space exploration. In the past few years, the tactical deployment of direct energy weapons based on fiber lasers has become a reality. The development of fiber lasers is rooted in a number of technical areas including optical materials, optical waveguide design, nonlinear optics, optical fiber fabrication, and optical characterization, in addition to optical fiber components, and fiber laser design and architecture. No comprehensive in-depth coverage of such diverse topical areas has appeared in a single book. Many important developments have taken place in the past decade in both academia and industry. This book comprehensively covers the basics, technology and applications of fiber lasers including up-to-date developments in both academia and industry and is aimed to serve as both an introduction and research aid for graduate students, engineers, and scientists who are new to this field and also for veterans in the field

MEMS for automotive and aerospace applications reviews the use of Micro-Electro-Mechanical-Systems (MEMS) in developing solutions to the unique challenges presented by the automotive and aerospace industries. Part one explores MEMS for a variety of automotive applications. The role of MEMS in passenger safety and comfort, sensors for automotive vehicle stability control applications and automotive tire pressure monitoring systems are considered, along with pressure and flow sensors for engine management, and RF MEMS for automotive radar sensors. Part two then goes on to explore MEMS for aerospace applications, including devices for active drag reduction in aerospace applications, inertial navigation and structural health monitoring systems, and thrusters for nano- and pico-satellites. A selection of case studies are used to explore MEMS for harsh environment sensors in aerospace applications, before the book concludes by considering the use of MEMS in space exploration and exploitation. With its distinguished editors and international team of expert contributors, MEMS for automotive and aerospace applications is a key tool for MEMS manufacturers and all scientists, engineers and academics working on MEMS and intelligent systems for transportation. Chapters consider the role of MEMS in a number of automotive applications, including passenger safety and comfort, vehicle stability and control MEMS for aerospace applications are also discussed, including active drag reduction, inertial navigation and structural health monitoring systems Presents a number of case studies exploring MEMS for harsh environment sensors in aerospace

The microelectromechanical systems (MEMS) industry has experienced explosive growth over the last decade. Applications range from accelerometers and gyroscopes used in automotive safety to high-precision on-chip integrated oscillators for reference generation and mobile phones. MEMS: Fundamental Technology and Applications brings together groundbreaking research in MEMS technology and explores an eclectic set of novel applications enabled by the technology. The book features contributions by top experts from industry and academia from around the world. The contributors explain the theoretical background and supply practical insights on applying the technology. From the

historical evolution of nano micro systems to recent trends, they delve into topics including: Thin-film integrated passives as an alternative to discrete passives The possibility of piezoelectric MEMS Solutions for MEMS gyroscopes Advanced interconnect technologies Ambient energy harvesting Bulk acoustic wave resonators Ultrasonic receiver arrays using MEMS sensors Optical MEMS-based spectrometers The integration of MEMS resonators with conventional circuitry A wearable inertial and magnetic MEMS sensor assembly to estimate rigid body movement patterns Wireless microactuators to enable implantable MEMS devices for drug delivery MEMS technologies for tactile sensing and actuation in robotics MEMS-based micro hot-plate devices Inertial measurement units with integrated wireless circuitry to enable convenient, continuous monitoring Sensors using passive acousto-electric devices in wired and wireless systems Throughout, the contributors identify challenges and pose questions that need to be resolved, paving the way for new applications. Offering a wide view of the MEMS landscape, this is an invaluable resource for anyone working to develop and commercialize MEMS applications.

A description of the inertial technology used for guidance, control, and navigation, discussing in detail the principles, operation, and design of sensors, gyroscopes, and accelerometers, as well as the advantages and disadvantages of particular systems. An engineer with long practical experience in the field, the author elucidates such recent developments as fibre-optic gyroscopes, solid-state accelerometers, and the global positioning system. This will be of interest to researchers and practising engineers involved in systems engineering, aeronautics, space research, and navigation on both land and sea.

Covers the latest developments in PNT technologies, including integrated satellite navigation, sensor systems, and civil applications Featuring sixty-four chapters that are divided into six parts, this two-volume work provides comprehensive coverage of the state-of-the-art in satellite-based position, navigation, and timing (PNT) technologies and civilian applications. It also examines alternative navigation technologies based on other signals-of-opportunity and sensors and offers a comprehensive treatment on integrated PNT systems for consumer and commercial applications. Volume 1 of Position, Navigation, and Timing Technologies in the 21st Century: Integrated Satellite Navigation, Sensor Systems, and Civil Applications contains three parts and focuses on the satellite navigation systems, technologies, and engineering and scientific applications. It starts with a historical perspective of GPS development and other related PNT development. Current global and regional navigation satellite systems (GNSS and RNSS), their inter-operability, signal quality monitoring, satellite orbit and time synchronization, and ground- and satellite-based augmentation systems are examined. Recent progresses in satellite navigation receiver technologies and challenges for operations in multipath-rich urban environment, in handling spoofing and interference, and in ensuring PNT integrity are addressed. A section on satellite navigation for engineering and scientific applications finishes off the volume.

Volume 2 of Position, Navigation, and Timing Technologies in the 21st Century: Integrated Satellite Navigation, Sensor Systems, and Civil Applications consists of three parts and addresses PNT using alternative signals and sensors and integrated PNT technologies for consumer and commercial applications. It looks at PNT using various radio signals-of-opportunity, atomic clock, optical, laser, magnetic field, celestial, MEMS and inertial sensors, as well as the concept of navigation from Low-Earth Orbiting (LEO) satellites. GNSS-INS integration, neuroscience of navigation, and animal navigation are also covered. The volume finishes off with a collection of work on contemporary PNT applications such as survey and mobile mapping, precision agriculture, wearable systems, automated driving, train control, commercial unmanned aircraft systems, aviation, and navigation in the unique Arctic environment. In addition, this text: Serves as a complete reference and handbook for professionals and students interested in the broad range of PNT subjects Includes chapters that focus on the latest developments in GNSS and other navigation sensors, techniques, and applications Illustrates interconnecting relationships between various types of technologies in order to assure more protected, tough, and accurate PNT Position, Navigation, and Timing Technologies in the 21st Century: Integrated Satellite Navigation, Sensor Systems, and Civil Applications will appeal to all industry professionals, researchers, and academics involved with the science, engineering, and applications of position, navigation, and timing technologies. pnt21book.com

This modern textbook guides the reader through the theory and practice of the motion and attitude control of space vehicles. It first presents the fundamental principles of spaceflight mechanics and then addresses more complex concepts and applications of perturbation theory, orbit determination and refinement, space propulsion, orbital maneuvers, interplanetary trajectories, gyroscope dynamics, attitude control, and rocket performance. Many algorithms used in the modern practice of trajectory computation are also provided. The numerical treatment of the equations of motion, the related methods, and the tables needed to use them receive particular emphasis. A large collection of bibliographical references (including books, articles, and items from the "gray literature") is provided at the end of each chapter, and attention is drawn to many internet resources available to the reader. The book will be of particular value to undergraduate and graduate students in aerospace engineering.

This book reports on new theories and applications in the field of intelligent systems and computing. It covers computational and artificial intelligence methods, as well as advances in computer vision, current issues in big data and cloud computing, computation linguistics, and cyber-physical systems. It also reports on important topics in intelligent information management. Written by active researchers, the respective chapters are based on selected papers presented at the XIV International Scientific and Technical Conference on Computer Science and Information Technologies (CSIT 2019), held on September 17–20, 2019, in Lviv, Ukraine. The conference was jointly organized by the Lviv Polytechnic National University, Ukraine, the Kharkiv National University of Radio Electronics, Ukraine, and the Technical University of Lodz, Poland, under patronage of Ministry of Education and Science of Ukraine. Given its breadth of coverage, the book provides academics and professionals with extensive information and a timely snapshot of the field of intelligent systems, and is sure to foster new discussions and collaborations among different groups.

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